Meeting minutes 2/6/2017

Location: Classroom

Attendance: all

What has changed from last meeting:

* Quintin
  + Refactored code relevant to face tracking
* Zach
  + Bugfixing battery stuff
  + Picked up the arduino board and ultrasonic sensor from lab to work on it remotely
* Alex
  + Updated ReadMes
  + Fixed security issue
  + Voice debugging
* Seattle
  + Helped with connecting sensor to arduino board remotely (away from stocker lab)

**Immediate goals:**

1. Group - update research expo details
2. Voice Recognition Team
   1. Alex - general active listening debugging, commands that move servos motors
   2. Kurtis - command to raise arm
      1. Will require writeing some servos motor code
3. Environmental Mapping
   1. Group - install arduino, test utrasonic beam signal
   2. Zach - fix bug with battery indicator
   3. Seattle (and Zach) - meet with Robocat to test arduino hardware
4. Facial Recognition/color Tracking
   1. Quintin - center on face with highest happiness rating, add in priority for highest happiness rating face, add side by side view of what cat can see
   2. Luke - integrate color tracking into FdActivity